

Title of the invention

METHOD AND SYSTEM FOR TRANSMISSION OF SIGNALS TO NODES IN A SYSTEM

Field of the invention

5 The invention relates to a method of transmitting signals, e.g. control signals, request signals, interrogation signals etc. to a node in the form of a controllable unit associated with a device, e.g. a controllable device, measuring means, etc. [as specified in the preamble of claim 1].

10 The invention further relates to a system for transmission of signals, e.g. control signals, request signals, interrogation signals etc. to a node in the form of a controllable unit associated with a device, e.g. a controllable device, measuring means, etc. [as specified in the preamble of claim 9].

15 Background of the invention

[Normally, prior art] systems for transmitting signals, e.g. controls signals to controllable devices such as openers for doors, gates, windows etc. have been provided in the form of wired control systems. Such systems, however, lacks user friendliness because the set up is inflexible, e.g. the use of mobile remote controls will not be possible.

[However, also] wireless systems have been provided, e.g. using radio frequency signals, infra red signals etc, whereby enhanced user friendliness may be provided,

25 e.g. by using wireless remote controls. However, such wireless solutions have a number of disadvantages; for example, the problem that a transmitted control signal may not always be received by the intended controllable device, e.g. because of less than optimal transmission circumstances, shielding effects caused by walls and other structures, etc.

30 Brief Summary of the invention

[It is an objective of the invention to provide] a method and a system for transmission of signals [as specified above], by means of which disadvantages related to these prior art systems may be avoided, to control various devices regardless of surrounding walls and structures.

It is an objective of the invention to provide a method and a system for transmission of signals according to an aspect of the invention as specified above, by means of which it will be possible to integrate control systems comprising a plurality of controlled units using both wireless and wired connection.

5 It is a further objective to provide such a method and a system by means of which it will be possible to prioritise the operations related to the controlled units comprised in the system.

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These and other objectives are achieved by the invention as explained in the following:

Summary of the invention

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More particularly

As specified in claim 1, the invention relates to a method of transmitting signals, e.g. control signals, request signals, interrogation signals etc. to a node in the form of a controllable unit associated with a device, e.g. a controllable device, measuring means, etc. and wherein said controllable unit may be linked to at least one further node by means of a communication bus, at least one of said nodes comprising radio frequency receiving means. Said method comprising the steps of the method include:

20 a) transmitting a signal from a controller,

b) reception of said signal by at least said node comprising radio frequency receiving means,

25 c) detection of at least part of said signal indicating a destination node, and

d) retransmission of said signal or part of said signal by said node comprising radio frequency receiving means to said destination node via said communication bus.

According to another aspect of the invention
30 a preferred embodiment, as specified in claim 2, the method may comprise a procedure for determining a timeslot in which said retransmittal may be performed by said node comprising radio frequency receiving means.

According to a further ^{aspect} preferred embodiment as specified in claim 3, said ^{the} procedure for determining a timeslot may comprise a random selection of a timeslot.

Advantageously, as specified in claim 4, said signal may be received by at least two nodes comprising radio frequency receiving means and said ^{the} retransmittal may be performed by the node for which the earliest occurring timeslot has been selected.

According to the embodiment specified in claim 5, said at least part of said ^{the} signal indicating a destination node may comprise an identification of the destination node, for example an address.

Preferably, as specified in claim 6, said ^{the} retransmittal of said received signal may be performed ^{via} means of a wired communication bus.

Advantageously, as specified in claim 7, said ^{the} signal may be transmitted to said ^{the} node comprising radio frequency receiving means by means ^{via} of a wireless remote control.

According to a further ^{aspect of the invention} preferred embodiment as specified in claim 8, the method may further comprise ^{can include} transmittal of a response signal from the destination node, said ^{the} response signal being transmitted via said ^{the} communication bus and by means of said ^{via the} node having transmitted the signal to the controller having transmitted said ^{the} signal, e.g. routing the response signal corresponding to the routing of said ^{the} signal.

The invention also relates to a system ^{as specified in claim 9} for transmission of signals, e.g. control signals, request signals, interrogation signals etc. to a node in the form of a controllable unit associated with a device, e.g. a controllable device, measuring means, etc. wherein said ^{in which the} controllable unit may be linked to at least one further node by means of ^{via} a communication bus, wherein at least one of said ^{the} nodes comprises radio frequency receiving means for reception of signals transmitted from at least one controller comprised in the system and wherein said ^{in which} at least one node comprising radio frequency receiving means for reception of signals have means for

retransmitting of a received signal or information comprised herein via ^{the} ~~said~~ communication bus.

In a preferred embodiment, as specified in claim 10, said system may comprise a plurality of said nodes in the form of controllable units, each associated with a device, and said system may comprise one or more communication buses, each defining a subnet in the system and each being linked to at least one of said nodes comprising radio frequency receiving means.

10 Preferably, as specified in claim 11, said nodes may comprise identification means, e.g. means for storing an e.g. address, and means for identifying an identification part of a received signal.

15 Advantageously, as specified in claim 12, said at least one node comprising radio frequency receiving means may comprise means for initiating a re-transmittal of a received signal or part hereof, e.g. in case of reception of a signal with an identification part different from the identification of the node in question.

20 Preferably, as specified in claim 13, said at least one controller may comprise remote control means for transmission of said signals to one or more of said nodes comprised in the system.

25 In a further embodiment as specified in claim 14, said communication bus may comprise a communication channel operating by means of wired connections.

30 Additionally, the
In a further preferred embodiment as specified in claim 15, said at least one of said nodes comprising radio frequency receiving means may comprise means for establishing and storing a table comprising identification of destination nodes linked by a communication bus, e.g. comprised in a subnet of the system.

In a still further preferred embodiment as specified in claim 16, said nodes may ~~can include~~ comprise power supply means, preferably connected to a plurality of said nodes by ~~the~~ via means of a power supply line.

5 Advantageously, as specified in claim 17, said communication bus ~~can also include~~ may comprise a communication channel operating by means of said power supply line, e.g. by means of a modulation technique, superimposing technique etc.

yet another aspect of the invention

10 In a still further preferred embodiment as specified in claim 18, at least one of said ~~can include~~ nodes on the subnet ~~may comprise~~ control means for performing a general control of simultaneously and/or sequentially performed operations by the devices involved in the system, e.g. in order to prioritise operations in consideration of certain resources such as available power etc, said ~~control means comprising~~ ^{having} means for keeping account of available resource(s), means for accepting or denying requests from nodes 15 on the subnet, means for aborting current operations of ~~said~~ ^{the} nodes and/or means for valuating requests and/or current operations in view of a priority value.

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The figures

Brief Description of the Drawings

The invention will be explained in further detail below with reference to the figures ⁱⁿ of which:

25 fig. 1 shows a general overview of a system comprising a plurality of nodes and a number of subnets according to the invention,

fig. 2 shows a general overview of a system according to a first embodiment of the invention,

fig. 3 shows a system according to another embodiment of the invention,

30 fig. 4 shows a receiver unit for use in connection with an embodiment of the invention,

fig. 5 shows a further receiver unit for use in connection with a further embodiment of the invention, and

fig. 6 shows a system according to a still further embodiment of the invention illustrated in a manner corresponding to figs. 2 and 3.

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Detailed description

Detailed reference will now be made to the figures in which examples embodying the present invention are shown. Repeat use of reference characters in the present specification and figures is intended to represent same or analogous features or elements of the invention unless otherwise indicated herein.

Fig. 1 shows a general overview of a system according to an embodiment of the invention. The system is generally designated 1 and comprises a plurality of units or nodes 6, 7, 8, 10, 11, 12, 16, 17, 18, 20, 21 and 22. Some of these nodes, e.g. 6, 7 and 8 are designed as controllers, e.g. control units by means of which it is possible to transmit control signals or other types of signals to one or more of the units or nodes U in the system.

15 The units or nodes 10, 11, 12, 16, 17, 18, 20, 21 and 22 are designed as controllable units or nodes, which are able to perform in response to a control signal or a similar form of received signal. Some or all of these units comprise radio frequency receiver/transceiver means as shown. These units or nodes are as illustrated located in subnets, e.g. 2, 3 and 4. A subnet ~~comprises~~ includes at least one unit which comprises RF receiver or transceiver means. A subnet may comprise only one node, but normally it

20 comprises a plurality of units, e.g. at least two. The actual number of nodes or units in a subnet will depend on the actual application, the actual physical location of the involved units and/or the utilization of the units. The units which are comprised in a subnet, which will also be referred to as a powerlink arrangement, will as shown be mutually connected by means of a bus system, e.g. 15, 19 and 23, respectively. This bus system may be a wired connection by means of which the units in a subnet may communicate with each other, ~~which will be explained further in the following~~ as *in greater detail below*.

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It will be understood that a system may comprise more or less than the illustrated three subnets, e.g. one, two, four etc. subnets or powerlink arrangements.

The drawings and the following description provide a full and detailed written description of the invention and the manner and process of making and using it, so as to enable one skilled in the pertinent art to make and use it. The drawings and detailed description also provide the best mode of carrying out the invention. However, the examples set forth herein are provided by way of explanation of the invention and are not meant as limitations thereof. The present invention thus includes modifications and variations of the following examples as come within the scope of the annexed claims and their equivalents.

Two of the illustrated controllers C, e.g. 6 and 7 are designed as remote control units, which are equipped with radio frequency transmitters or transceivers in order to be able to communicate with the units U equipped with RF receivers or transceivers. A system according to the invention will have ~~to comprise~~ at least one controller which 5 may communicate with the units ~~by~~^{wire} means of RF signalling etc.

However, a system may also comprise other types of controllers C, for example a controller 8 which will be able to transmit signals to one or more of the units U by e.g. wired means, e.g. by electric signalling, by means of infra red signalling, other 10 means of optical signalling, electromagnetic signalling etc.

The operation of a system according to the invention will now be explained with reference to fig. 2, which illustrates (part of) a system with a subsystem having only one unit U with RF receiving/transceiving means. The system ~~comprises a plurality~~^{includes one or more} 15 of units or nodes 30, 31, 32, 33 (U1 – Un) comprising or linked to, for example, drive units for various devices 35, 36, 37, 38. These devices may, for example, be activators of various types and used in a wide variety of applications, as explained in further detail later on. The units may also or instead comprise or be linked to assorted apparatus, measuring devices, indicating devices, controllers etc. that need to receive 20 information, control signals etc. at certain points of time. A common feature of the units 30, 31, 32, 33 is that it is necessary or advantageous to be able to send some sort of information, signal etc. to the units. Further, it may be necessary or preferable to be able to receive information or signals from the units, e.g. confirmation signals, acknowledge signals etc.

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In the embodiment shown in fig. 2, the unit 31 is equipped with receiving means for radio frequency signals, e.g. including antenna means 40. Each unit ~~comprises~~^{includes}, e.g., a motor drive unit or a control unit and is connected to a driven or controlled member 35, 36, 37, 38. It will be understood that the means driven by, controlled by etc. the 30 unit may be integrated with the unit.

The system further comprises a node in the form of a controller, e.g. a remote control unit 42 designed for transmission of signals by means of radio frequency transmission means, e.g. including antenna means 43. This remote control unit may be used for transmitting control signals or other types of signals to one or more of the 5 units or nodes U1 – Un in the system.

Fig. 2 further shows that
~~As illustrated, the system may comprise~~ *can include*
at least one additional controller, e.g. a remote control 44, similar to the first remote control, e.g. designed for transmission of signals by means of radio frequency transmission means, e.g. including antenna 10 means 45, or dissimilar to the first remote control, e.g. designed for transmission by other means such as wired means, infra red transmission means etc. as explained above.

The units 30, 31, 32, 33 are as illustrated and as explained above connected by 15 communication means 50 which is in the form of a wired communication bus. The communication may be performed in accordance with a predefined protocol whereby the communication means 50 may serve to facilitate at least one function or service, or a combination of such functions or services, of a number of functions or services related to the operation of the system, e.g. regarding the reception and/or transmittal 20 of signals, regarding the operation of the respective units etc. These functions or services and options thereof will be further described in the following.

When a signal is transmitted from a controller, e.g. a remote control, for example the 25 remote control 42, ^{in Fig. 2} the signal will in a first preferred embodiment be received by one of the units 30, 31, 32, 33 which is provided with the RF receiving means and which will be designated as a master unit, in the illustrated example, the unit 31. The received signal, e.g. a frame or data packet will include information, e.g. an address, regarding the destination node, e.g. the intended unit, and the master unit 31 will determine the addressee of each received signal.

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If the addressee, i.e.. the destination node is the master unit itself, it will act in accordance with the information included in the received signal. If the addressee is

one of the other units, e.g. the unit 33, the master unit 31 will retransmit the received signal, ^{via} ~~by means of~~ the communication channel 50 and in accordance with the protocol for the communication. Each of the other units 30 will read the signal, but only the unit addressed in the signal, e.g. the unit 33, will receive the signal and act
5 in accordance with the payload data information, e.g. a command, included in the signal.

The master unit, e.g. the unit 31 may comprise a table containing a list of addresses of all nodes or units comprised in the system, i.e. the subnet connected by the
10 communication bus 50. This table is established when the subsystem is powered up. If such a table is established, the master unit will be able to determine whether the destination node(s) contained in a received signal, e.g. a received frame of a message, is located in the subnet associated with the master unit in question. If this is the case, the message will be retransmitted via the communication bus 50. If not, e.g.
15 because the destination node is comprised in another subnet associated with the system, the message will not be retransmitted. If the destination node is the unit itself, i.e. the unit which received the RF-signal, the message will not be retransmitted either. The establishment of such a table may be omitted in which case all signals will be retransmitted, whereby unnecessary retransmittals may be
20 performed, but whereby data processing and storage may be avoided/reduced.

A signal transmitted from a remote control, e.g. 42, may be addressed to more than one of the units in the system or even to all of these. In this case the signal will as described above be received by the master unit, e.g. 31 and the destination nodes,
25 e.g. the intended receivers will be determined by the master unit. The signal may be retransmitted to the other units in question via the communication bus 50, and the commands included in the signal may be performed by the units in question.

In a modified embodiment the master unit, e.g. the unit equipped with RF receiving/transceiving means may be able to perform a sequential operation of the commands involved in a received signal. When a signal is received, the master unit
30 will determine the intended receivers and possibly also the type of command(s)

included in the signal, e.g. possibly related to each of the intended receivers. On the basis of this information, in accordance with the protocol and possibly in accordance with other predefined rules for the operation of the system in question the master unit may retransmit the signal, e.g. transmit individual signals comprising individual
5 addresses and corresponding commands in a sequential order and possibly with individual and/or predetermined time intervals.

Further, the transmittal of the individual control signals may as mentioned be performed in accordance with specific rules. For example, when a given first signal
10 has been retransmitted to a first unit, the transmittal of the next signal to a second unit may be performed in dependence on a signal from the first unit, e.g. a signal confirming receipt of the first signal, confirming that the command has been performed or a signal implying that the command has not been performed. The transmittal of the next signal may then be performed, possibly after a predetermined
15 time interval. Other rules may be defined.

Further, the operation of the system in accordance with the communication protocol may include handling of control signals emitted from two or more remote controls and/or a plurality of control signals emitted from a single remote control, for
20 example control signals transmitted when the system is actually performing operations relating to a preceding control signal, e.g. a control signal from the same remote control or from another remote control associated with the system.

In such circumstances the master unit, e.g. the unit equipped with RF receiving/transceiving means may perform the operations in accordance with predefined rules, which may be established with regard to the actual application and the actual needs. For instance, the master unit may of course complete current operations before investigating further received signal(s) and operating in accordance with these. Instead, the master unit may determine the address(es) and control
25 content of a subsequently received signal and may, in accordance with pre-established rules, abort some or all of the current operation(s) and initiate some or all of the operations indicated by the subsequently received signal. This may for

example be the case if the subsequently received signal demands an operation to be performed which is in contradiction to a current operation, e.g. in the case of a system comprising operable windows where a current operation involves the opening of at least one window and where a subsequent signal indicates the closing of at least 5 the same window.

As shown in fig. 3 more than one of the units or nodes 30 - 33 in a subnet or powerlink arrangement may comprise means, e.g. including antenna means 40, 46, 47, 48 for receiving control signals from e.g. remote controls 42, 44.

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In this case the involved units, e.g. the units designed for receiving RF signals and connected to the same subnet, will operate on equal terms, i.e. none of these units will be designated as a master unit per se. The units equipped with RF receiving means will serve to help each other, since a signal transmitted from a remote 15 controller will have a larger chance of being (correctly, e.g. checked by Cyclic Redundancy Check - CRC) received by at least one of these units than if only one unit in a subnet is able to receive RF control signals. This is of particular importance when the units in a subnet is placed in locations where dampening of RF signals may occur, e.g. caused by walls or other building structures, furniture, etc. and caused by 20 the distances between the nodes, e.g. between a controller and a unit in a subnet. In these cases the transmitted control signal may be picked up by one of the units equipped with RF receiving means, e.g. the unit closest to the remote controller or located in a "free line of sight" in relation to the remote controller. The unit that receives the signal, will as previously described determine the destination node, 25 check the address table for the destination address and retransmit the signal, e.g. the frame or data packet, if the destination node is associated with the subnet in question and if the destination node is not the unit itself. If the unit does not comprise an address table, the signal will be retransmitted via the communication bus 50 in all cases as explained above.

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If, however, more than one of the units equipped with RF receiving means, e.g. RF-nodes receive an emitted control signal correctly (e.g. checked by Cyclic

Redundancy Check - CRC), these units will all be prepared to retransmit the signal. According to the invention the RF nodes that have received a signal will randomly select a timeslot. A system according to the invention may for example operate with 32 timeslots, and each of the RF-nodes that have received a signal will pick one of 5 these. When the respective timeslots occurs, the RF-nodes in question will initiate the retransmission via the communication bus 50. The RF node that have selected the lowest, i.e. the earliest occurring timeslot, will retransmit the signal, e.g. the frame or packet. The other RF-nodes (or -node) that also have received the signal, will detect that a transmission is occurring via the communication bus and will randomly pick a 10 new timeslot number and will try to transmit when this timeslot occurs and when the communication bus is vacant.

If two (or more) RF nodes have selected the same timeslot number, they will try to transmit simultaneously. However, the system comprises a collision detection 15 arrangement and in such cases the transmission will be aborted. The RF nodes trying to perform a retransmission of a received signal will each randomly select a new timeslot number, and a retransmission will be performed by the node that has selected the lowest timeslot number in analogy with what has been explained above. However, in order to reduce the chance of a new collision, the number of timeslots 20 may be enlarged, for example doubled, when the new timeslot number is selected. This procedure may be repeated if a new collision occurs.

A node which is in the process of initiating or performing a transmission of a received signal, will abort the transmission if it is detected that the signal, e.g. a 25 frame, that is to be transmitted, is received in e.g. a receiver buffer of the node. This will occur if another node already has retransmitted the signal, e.g. the frame with the same content, and in these cases the system according to the invention will prevent that a signal, e.g. a frame or a data packet, is needlessly retransmitted (one or more times in addition to the "original" retransmission).

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It will be understood that the same process, e.g. the selection of a timeslot number etc. may also be performed by a RF node which is the only RF node associated with

a subnet. Thus the RF nodes may be designed similarly, irrespective of the actual use.

When a destination node on a subnet has received a signal, e.g. a frame, a response, 5 e.g. an acknowledgement, a measured value etc. normally has to be transmitted from the destination node back to the controller, e.g. the remote control unit. This response will according to the protocol for the communication be routed along the same route as the received signal, e.g. the control signal.

10 This may be illustrated with reference to fig.1. Supposing that the subnet 3 contains two nodes with RF receiving means, e.g. 16 and 17, and that a control signal is transmitted from the remote controller 6 with the unit 18 as the destination node. The signal is (correctly) received by e.g. the RF node 16 and retransmitted via the communication bus 19 to the node 18. A response signal from the node 18 will be 15 routed via the RF node 16 back to the remote controller 6. Since the control signal was received by the RF node 16 instead of the RF node 17, it may be expected that transmission between the node 16 and the controller 6 will again lead to a positive result, and thus a relatively high transmission success rate for the response signals back to the remote controllers may be expected.

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The embodiment illustrated in fig. 3 will have the advantage that a control signal emitted by a remote control from a position giving inadequate reception at the position of a unit equipped with RF receiving means, e.g. 31 may be received by another unit, e.g. 31, 32, 33 instead, whereby it is assured that a system according to 25 the described embodiment will have improved reception of control signals in cases where the remote control, or rather the remote control operated by a user, is situated far from the one or more of the units or at a place giving a reduced transmission.

A controllable unit or node, e.g. 10, 11, 12, 16, 17, 18, 20, 21, 22 according to the 30 invention will be described in further detail with reference to fig. 4, where a controllable unit or node is generally designated 30 and where the main parts of an embodiment of a controllable unit according to the invention are illustrated. As

described above, this unit comprises antenna means 46 connected to receiver or preferably transceiver means 51 for reception of control signals. It will be understood that according to the invention wired means may be used additionally for transmitting control signals to the unit 30 if found applicable. The 5 receiver/transceiver means 51 is connected to an internal bus 52 for connection to e.g. processor means 53, control means 54 and power supply means 56. The processor means 53 is designed and/or programmed to perform in accordance with the protocol according to the invention and in accordance with user-specified and/or application-specific conditions, including control of the communication via the 10 communication bus 50. The control means 54 is designed to perform the required operations, e.g. control, interrogation etc. and may be connected by means of wire, wireless transmission etc. 55 to various devices (not shown in fig. 4). The power supply means 56 may be designed in various manners, which will be evident to a skilled person, e.g. as battery supply, as a mains fed transformer supply, as a local 15 DC-power supply, e.g. a 24V power supply, as a solar cell power supply, and combinations of these and other known power supply systems. Further, it will be understood that the power supply 56 may also supply power to the control and operation of the various devices connected to the unit.

20 A further embodiment of the controllable unit or node according to the invention is illustrated in fig. 5. As described above, the unit comprises antenna means 46, receiver means 51, an internal bus 52, processor means 53, control means 54 and a power supply 56'. The power supply 56', however, is feed with power via a connection part 57 from a common power supply bus 60, e.g. a two-cord cable or the 25 like, connected to a power supply unit 58 which may be common to all units or nodes in a subnet or powerlink arrangement according to the invention. This power supply bus 60 also serves as a communication bus for the communication between the controllable units or nodes comprised in a subnet or powerlink arrangement according to the invention. The communication may be performed in a number of 30 ways, which will be obvious to a skilled person, e.g. as modulated communication, super positioned communication etc. The power supply 56' may provide the link between the unit 30 and the communication bus/power supply bus 60 via the

connection part 57, thus operating as filtering means for transferring communication signals to/from the internal bus 52.

Finally, a further embodiment shall be described with reference to ¹fig. 6, which
5 shows a system comprising a subnet or a powerlink arrangement according to the invention in a manner corresponding to figs. 2 and 3.

Here, the communication between the controllable units 30 - 33 according to the invention is performed via a separate and designated communication bus 50, which
10 may perform its operation by means of wired means. Further, it is shown that the power supply to units 30 - 32 and preferably also the associated devices 35 - 38 is provided by means of a central/local power supply 58 connected via a power supply bus 62 and connections 64 to the respective units/nodes/devices.

15 Further, according to an embodiment of the invention, the described method and system may be utilized for monitoring and/or controlling the power consumption and/or demand or other (limited) resources related to the operation of the system, which will be explained in further detail in the following.

20 The power available from e.g. the power supply unit 58 will in practise be limited, e.g. in view of peak current, rated power value etc, of the power supply unit and the wiring. Thus, it will be understood that if e.g. two electric motors providing the operative power for two of the devices 35 - 38 are operated simultaneously, the power supply and the wiring will have to be designed and rated in correspondence
25 with this and it will be understood that savings may be achieved if such simultaneous loads can be avoided.

In accordance with an important aspect of the invention, a node on a subnet may be designated as a resource master, e.g. in order to control consumption of a scarce
30 and/or limited resource. Such a resource may for example be the available power, cf. what has been explained above, but other types of resources may be the objects of the resource master control according to this embodiment of the invention.

The node that is designated the resource master is selected in accordance with a predefined rule, e.g. the node having the lowest or the highest address on the subnet. Other means of designating a node as resource master may be utilized which will 5 be obvious to a skilled person.

When a node on the subnet has received a command implying that an amount of the limited resource, e.g. the operating of an electric motor demanding a current of e.g. 1A, will have to be provided to the node, the node in question will have to send a 10 request to the resource master via the communication bus. The resource master will determine the available resource, e.g. in view of other nodes using the resource at the same time or requesting to use the resource at the same time. If the demanded resource is available, the resource master will respond to the requesting node, that the required resource may be used. If the demanded amount of the resource is not 15 available, the requesting node will be told to wait. When the required resource becomes available, the resource master will tell the requesting node that it may now initiate the operation.

However, the request from a node may also comprise a priority, whereby the 20 resource master, if other nodes are currently using resource, e.g. power, for operations with lower priority, may abort one or more of these lower prioritized operations, thus making the required amount of the resource available to the node with the higher prioritised request. When the higher prioritised operation is completed, the resource master will indicate to the node or nodes, which had the 25 operations aborted that they may proceed with these since the demanded power will now again be available. The priority will be related to the actual operation that the requesting node wishes to perform, and not the node itself. For example, a node requesting to use power for closing a window because a rain sensor has indicated that it is raining, may have a higher priority than a node requesting power for the 30 operation of a window blind etc.

It will be understood that if such a power consumption control (or control of another resource) is to be performed, the system or the subnet in question will need to contain a table comprising a listing of the addresses of the units in a subnet and possibly other information, e.g. rated power consumption, functionality of associated controlled device etc. Further it will be understood that the communication bus will provide means for communicating requests, control signals and responses from the resource master and that all nodes connected to the same source of resource will be controlled by the resource master, e.g. all nodes on a subnet.

5 When operating the devices etc associated with the controllable units, certain security or safety aspects may be involved, for example whether a particular remote control may perform e.g. an unlocking of a door, opening of a window etc. In such circumstances, the system according to the invention may be configured to provide that the decision whether a particular device may be operated upon reception of a

10 certain control signal from a particular controller is placed at the destination node. Thus, the security level and parameters will be determined by the set up of the controllable node operating a particular device, and the transmission and retransmission will be insensitive of such security and/or safety aspects.

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20 certain control signal from a particular controller is placed at the destination node. Thus, the security level and parameters will be determined by the set up of the controllable node operating a particular device, and the transmission and retransmission will be insensitive of such security and/or safety aspects.

25 The invention has been described above in general, but it will be understood that the invention may be particularly advantageous in connection with remote control of devices related to buildings, homes etc, where obstructions for a transmission of RF signals may be present. Such devices may be e.g. controlled aperture members such as operable windows, doors etc, having a member which maybe opened and closed.

30 It will also be understood that the invention is not limited to the particular examples described above but may be used in connection with a wide variety of applications. Further, it will be understood that the system according to the invention may be

designed in a multitude of varieties within the scope of the invention as specified in the claims.